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Jaffer, A.G.;
Radar Conference, 2002. Proceedings of the IEEE
22-25 April 2002 Page(s):294 - 297
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- ☐ **3. Locally optimal covariance matrix estimation technique for processing applications**
Abramovich, Y.I.; Spencer, N.K.; Gorokhov, A.Y.;
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Volume 2, 31 Oct.-2 Nov. 1994 Page(s):770 - 774 vol.2
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Cybernetics (Cat.No.02EX583)
[Machine Learning and Cybernetics, 2002. Proceedings. 20](#)
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Rothberg, E.; Gupta, A.;
[Supercomputing '90. Proceedings of](#)
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... systems via receding horizon control Lyapunov functions M. S. naier and J. Cloutier

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J. Tenny and James B. Rawlings Department of Chemical Engineering University ...

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MJ Tenny, SJ Wright, JB Rawlings - Report TWMCC-2002-02, 2002

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MJ Tenny, SJ Wright, JB Rawlings - Comp. Optim. Appl, 2002

Cited by 1 - [Web Search](#)**Towards a Sampled-Data Theory for Nonlinear Model Predictive Control - group of 2 »**

R Findeisen, L Imsland, F Allgower, B Foss - LECTURE NOTES IN CONTROL AND INFORMATION SCIENCES, 2003 - Springer

... Summary. This paper considers the stability, robustness and output feedback problem for sampled-data nonlinear model predictive control (NMPC). ...

Cited by 4 - [Web Search](#) - [BL Direct](#)**[PS] Computational Strategies for Nonlinear Model Predictive Control**M Tenny - [che.wisc.edu](#)... Stephen J. Wright ... Predictive Control Matthew Jeremy Tenny ... 79 Chapter 6 Nonlinear
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45(8):1649-1659, August 1999. [3] R. Fletcher. ...
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L. Chisci, G. Zappa: "Square-root Kalman filtering of descriptor systems", Systems
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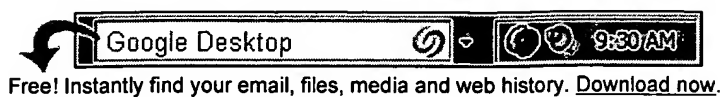
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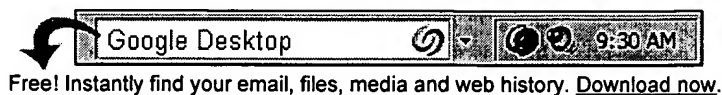
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